



GLAST ACD Segmentation Trade Study

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ACD Subsystem
ACD segmentation and the
efficiency requirement at 300 GeV
March 13, 2001 IDT phone call
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Study Motivation

- The goal is to understand the impact on the LAT effective area and geometry factor if the number of ACD tiles is reduced.
- Since the overall ACD dimensions are frozen, reducing the tile number implies using larger tiles.
- Larger tile area results in higher self-veto probability, which reduces the GLAST sensitivity, increasingly at higher energy.
The goal of the study is to determine the importance of this effect in a specific case.
- Current ACD design has 145 tiles (290 channels).
 - An additional 16 (TBR) channels for scintillating fibers tapes if needed to seal the gaps.
- Reducing number of tiles would save
 - Money and time - handling, testing and integrating.
 - Power, parts and complexity (and a little mass)
- Remove any remaining concerns about “real estate” for electronics



Not a background study

- Eventually, the impact of any change in segmentation must be vetted in GLASTSIM.
 - There is no efficient way to do this at the present time.
 - Background rejection does have cuts on number of tiles hit but because of the way this cut is used, **changing the segmentation will have a negligible impact (S. Ritz, 2000).**
- Otherwise the segmentation in the bottom two rows is not currently used in the background cuts.
- Selection/background rejection cuts for high energy electrons are now being developed by Taro Kotani and Steve Ritz.
 - Need 0.9 from the tracker to go with 0.9997 ACD efficiency to reach required <1 false photon in 3×10^4 electrons
 - 0.9 is just the live fractional area of a tracker layer
 - Probably ok for top entry
 - Side entry requires some “fiducial volume” cut
 - **No one has yet validated this number by simulation or determined the effect of this cut on effective area.**



Segmentation trade study

- 25 tiles on the top, 120 on the sides
 - Lower two rows dominate
 - 80 tiles nearest calorimeter
- Do analysis at 300 GeV
 - The self-veto problem increases as a function of energy
 - The required depth of calorimeter to obtain a given energy resolution also increases as a function of energy
- Self-veto and hence ACD segmentation affects both projected effective area A_p and geometry factor $A\Omega$, “G”
- Science most affected: search for gamma ray lines
 - Point sources of dark matter
 - Galactic center
 - Clumps in the halo
 - Isotropic high latitude diffuse component from galactic halo



Sensitivity to gamma-ray lines

GLAST sensitivity for the “dark matter point source” such as the Galactic Center

$$I_{\gamma} = \frac{n_{\sigma}}{0.68 \sqrt{A_{cal} f_t T}} \sqrt{2\eta E_{\gamma} (F_{GC} + F_b \Delta\Omega)}$$

and for a high latitude diffuse component

$$I_{\gamma} = \frac{n_{\sigma}}{0.68} \sqrt{\frac{2 F_b \eta E_{\gamma}}{A_{cal} \Omega T}}$$

- The lower I_{γ} , the better.
- Off axis, calorimeter gets thicker, and η decreases but so does A .

I_{γ} and E_{γ} are the line intensity and energy,

n_{σ} is the desired significance (in σ),

$\eta = \Delta E / E_{\gamma}$ is the relative energy resolution (half width containing 68% of events),

$2\eta E_{\gamma}$ is the bin width,

A_{cal} is the sensitive area,

T is the observation time,

f_t is the fraction of time (~ 0.25) during which the source lies in a good direction,

F_{GC} is the differential gamma-radiation from the source,

F_b is the background flux,

$\Delta\Omega = 10^{-3}$ sr is the point-spread function for the calorimeter, and $A_{cal} \Omega$ is the geometric factor.



Tile segmentation requirement

- Requirement flowdown from SRD
 - **Effective area on axis: $>8000 \text{ cm}^2$, goal $>12,000 \text{ cm}^2$**
 - Peak, 1-10 GeV, including loss due to background rejection
 - Energy resolution: 0.1-10 GeV, $<10\%$, goal 8%
 - **Energy resolution $>60^\circ$, $>10 \text{ GeV}$: $<6\%$, goal $<3\%$**
 - SRD does not specify the effective area we need at $>60^\circ$
 - Explanatory footnote: "Effective area for side incidence is 0.1 to 0.2 that of normal incidence for high resolution measurements."
 - **$\Delta E/E$ Goal implies calorimeter depth of 15-18 (TBR) Xo**
- Don't forget electron background rejection
 - **Selection: we must require at lease one tracker layer with "no- hit" be in the path of these events and the ACD must not be "hit" either.**



LAT systems specification

- LAT Performance Specification 5.2.1
Energy range: 20 MeV to >300 GeV,
A_{eff} >300 cm² (TBR) at 20 MeV, >3000 cm² at 100 MeV,
>6400 cm² (TBR) at 300 GeV.
Goal: >1000 cm² at 20 MeV, >8000 cm² at 100 MeV and
>9500 cm² at 1 TeV.
- LAT Performance Specification 5.2.2
Resolution: normal incidence gamma rays
<50% (TBR) 20 - 100 MeV, <10% 0.1 - 10 GeV,
<20% (TBR) 10 - 300 GeV.
Resolution goal: >60 degrees off-axis: <3% above 10 GeV.
- LAT Performance Specification 5.2.3
Peak effective area: >8000 cm² after background rejection
Peak effective area goal: >10000 cm² after background rejection



ACD Level 3 specification

As of today, the DRAFT ACD Level 3 subsystem specification says:

- 5.6: False VETO due to Calorimeter Backsplash
 - **<20%** of otherwise accepted gamma-ray events at 300 GeV shall be rejected by false VETOs due to calorimeter backslash

Can meet the LAT Requirement: $A_{\text{eff}} > 6400 \text{ cm}^2$ (TBR) at 300 GeV.

Goal: $> 9500 \text{ cm}^2$ at 1 TeV.

- If peak A_{eff} at 10 GeV meets 8000 cm^2 spec, then **0.8** x $8000 = 6400 \text{ cm}^2$.
 - This led to **>0.8** ACD Level 3 specification



ACD: Backsplash Measurements

- Backsplash measured from 5 to 300 GeV (SLAC and CERN)
- Agrees with simulations to approximately factor of 2
 - Spectra are different
 - Angular distributions are different

$$P_{Backsplash} = \left\{ 0.85 * \frac{0.3}{E_{thr}} + 0.15 \right\} * 10^{-3} * \frac{A}{144} * \left(\frac{55}{x + 10} \right)^2 * E^{0.75}$$

Where E is the energy of incident electron/photon in GeV

E_{thr} is the threshold value in units of mip

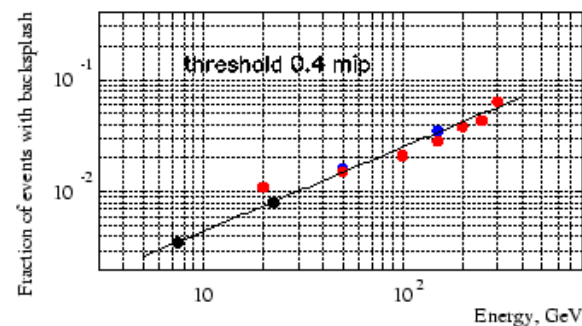
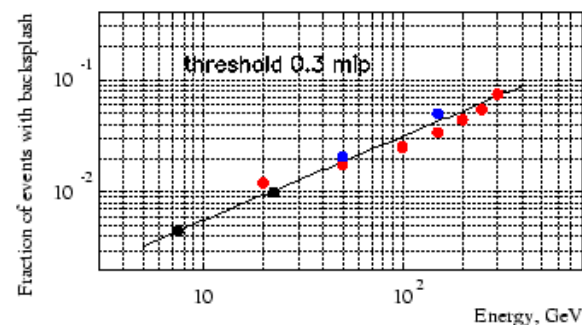
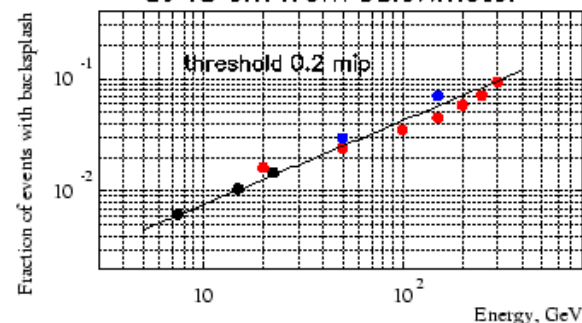
X is the distance from the top of calorimeter

A is area in cm²

$P_{backplash}$ is the probability that there was an energy deposition above E_{thr} in 1cm scintillator

- SLAC-97
- CERN-99
- CERN-99 (ACCESS calorimeter)

Backsplash in 144 sq. cm tile
at 45 cm from calorimeter





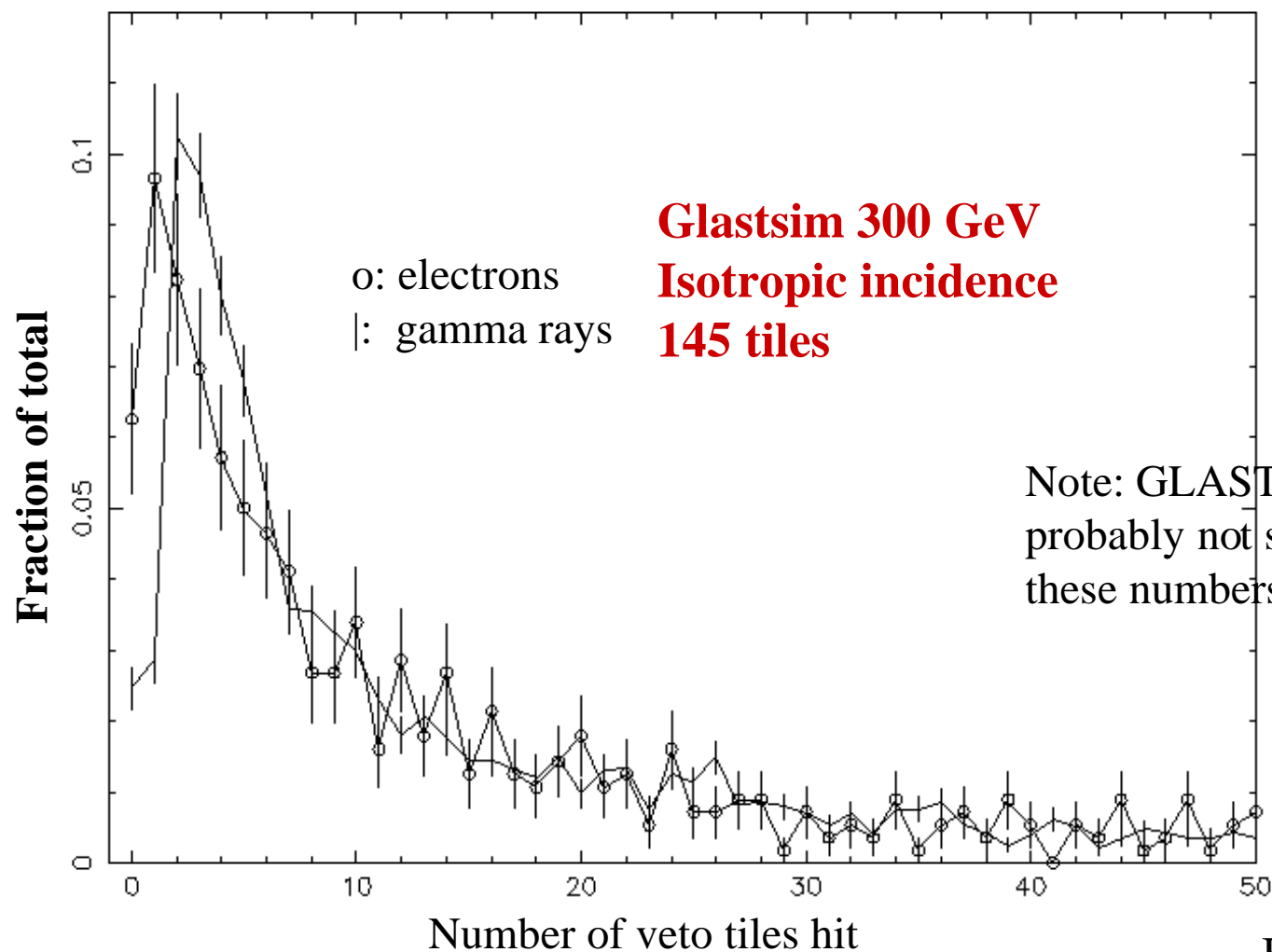
Simulation studies

- GEANT-3 and GLASTSIM studies were made to compare with measurements of backslash ($E_{\text{deposit}} > 200 \text{ keV}$)
 - Unresolved differences at high angle (90° to beam):
 - GEANT sims give 2 x more than observed
 - GLASTSIM gives 2.5 times fewer photons crossing the ACD than GEANT
 - Unresolved differences near beam in GLASTSIM (ok in GEANT)
 - Did not produce observed isotropic distribution
 - Did not produce energy dependence
- GEANT-3 studies by Alex
 - SLAC beam test '97
 - Sims 40% below measured
 - Reproduce proper angular distribution within 60° of beam
 - CERN test with deeper 40Xo Pb/SciFi calorimeter
 - Sims ~25-40% low at 20 GeV decreasing to 10% at 1 TeV
 - Sims suggest steeper slope than observed
- GEANT self-veto probabilities are <40% low.
 - GLASTSIM would be even lower

Design segmentation to measurements.



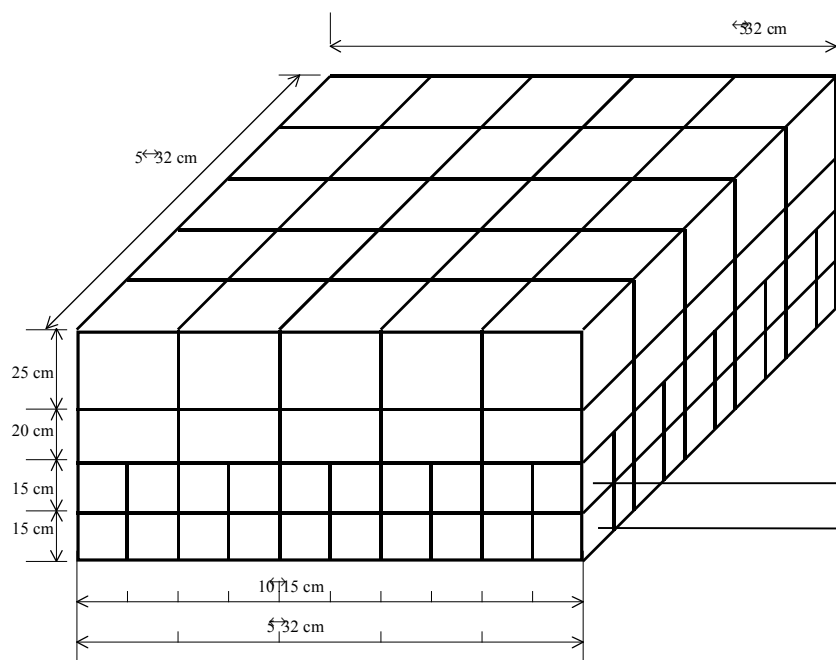
Distribution of number of tiles hit



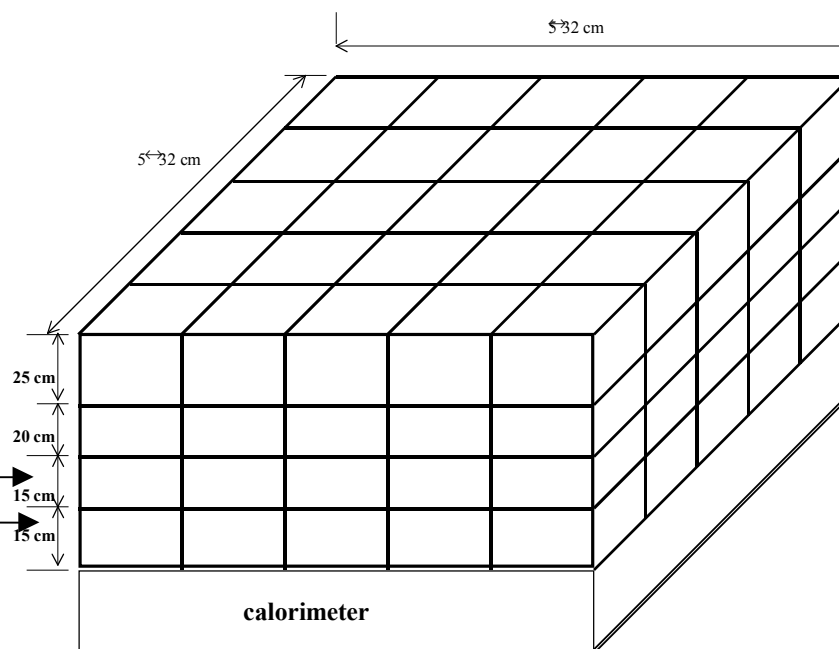
By Taro Kotani



Design configurations



Baseline (145)



Reduced segmentation (105)



Study Approach

- Designs being compared
 - “baseline design” (aka Proposal design)
 - “reduced segmentation design” (aka design “A”)
- Configurations were illuminated by muons
 - muons exclude interactions
 - studying only geometric effects
 - uniform flux over the ACD
- 2 cases were studied:
 - isotropic flux to study the Geometric factor, $G = A\Omega$
 - parallel flux (as function of zenith angle Θ and for $\Phi=0^\circ$ and 45°) to study effective area A
- Illumination was separable into events entering the instrument through the top of the ACD (Tracker) and separately through each side tile row.



Study Approach (cont.)

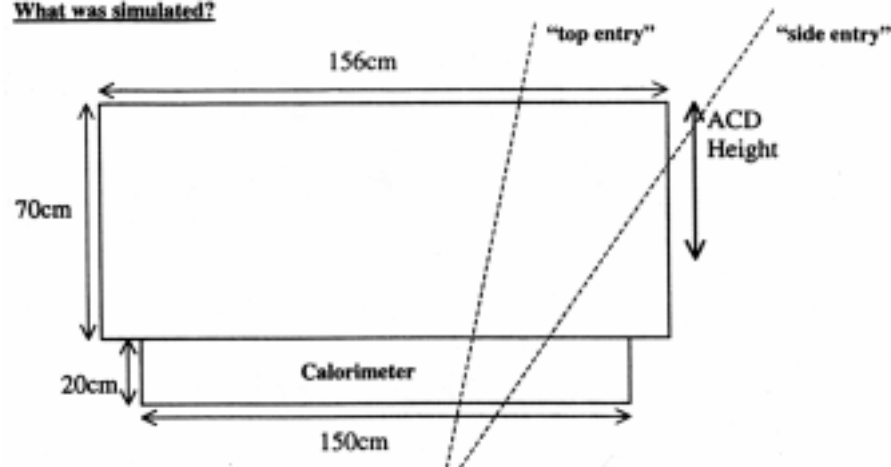
- The events were required to enter >6 cm above the bottom of ACD (top of the calorimeter). This reflects the requirement for the events to pass at least 2 Si planes.
- The self-veto of false hit probability was calculated using the formula obtained by beam tests at SLAC and CERN (Moiseev and Ormes, in preparation).
- For every event the path in the calorimeter, the distance between the entry points to the ACD and the calorimeter were calculated. This distance corresponds to x in the formula. An energy of 300 GeV and a VETO threshold of 0.3 mip were used in the simulations.
- Calorimeter was assumed to be 20cm (8.5 X_0) thick. Paths were required to traverse both the top and bottom surfaces of the calorimeter.
- Probability of backsplash was calculated for known tile area.



Impact on Area and Geometry

Simulation of the GLAST geometrical factor for long paths in a calorimeter

What was simulated?



Row heights on side
Front to Back
Aka Top to Bottom
25, 20, 15, 15 cm

- Total height of side = 70 cm above calorimeter.
- Entry must be >6cm above top of calorimeter to traverse 2 tracker layers.

Our effective area

– Point sources

or geometry factor

– Isotropic source

at a given energy resolution

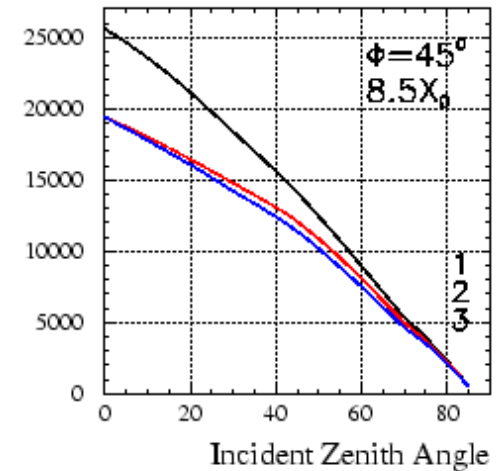
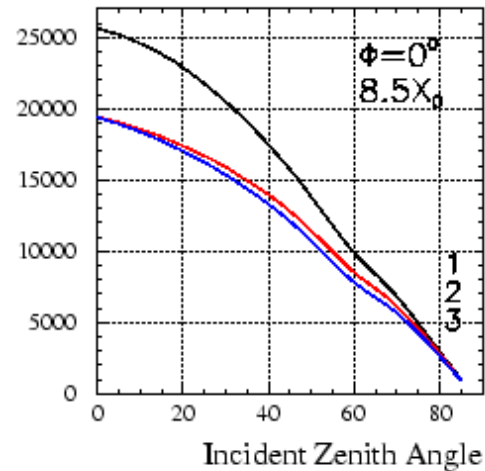
– depends on the depth of calorimeter desired.



Projected area, top + side entry

- **Line 1 (black) - projected area vs.. Incident angle**
 - Azimuthal angle extremes
 - $>8.5 X_o$ and $>15X_o$
- **Line 2 (red) - same, reduced for backslash**
- **Line 3 (blue) - same as red, reduced segmentation in 3-rd and 4-th rows**

Effective area, reduced for backslash

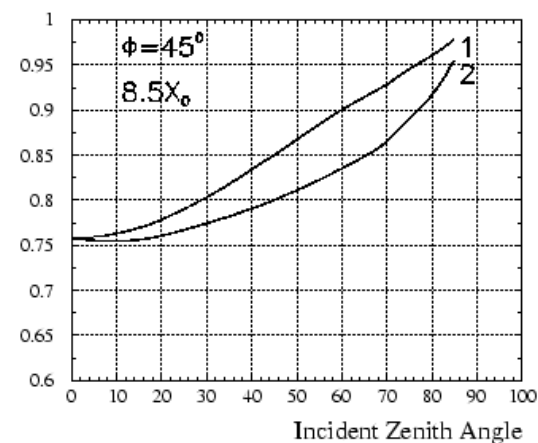
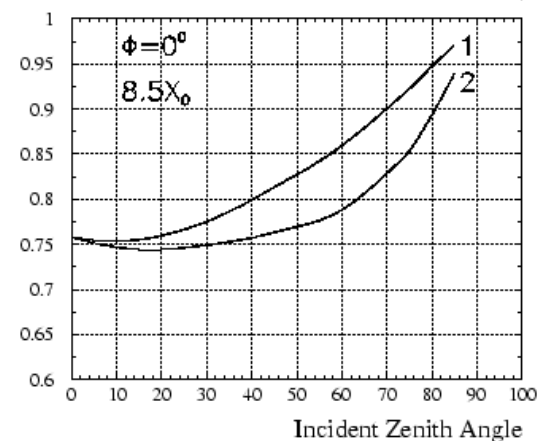




Projected area reduced for self-veto: 300 GeV

- Top plus all 4 ACD side rows are used; events are required to enter 6 cm above the calorimeter.
- Line 1 - baseline
- Line 2 - reduced segmentation

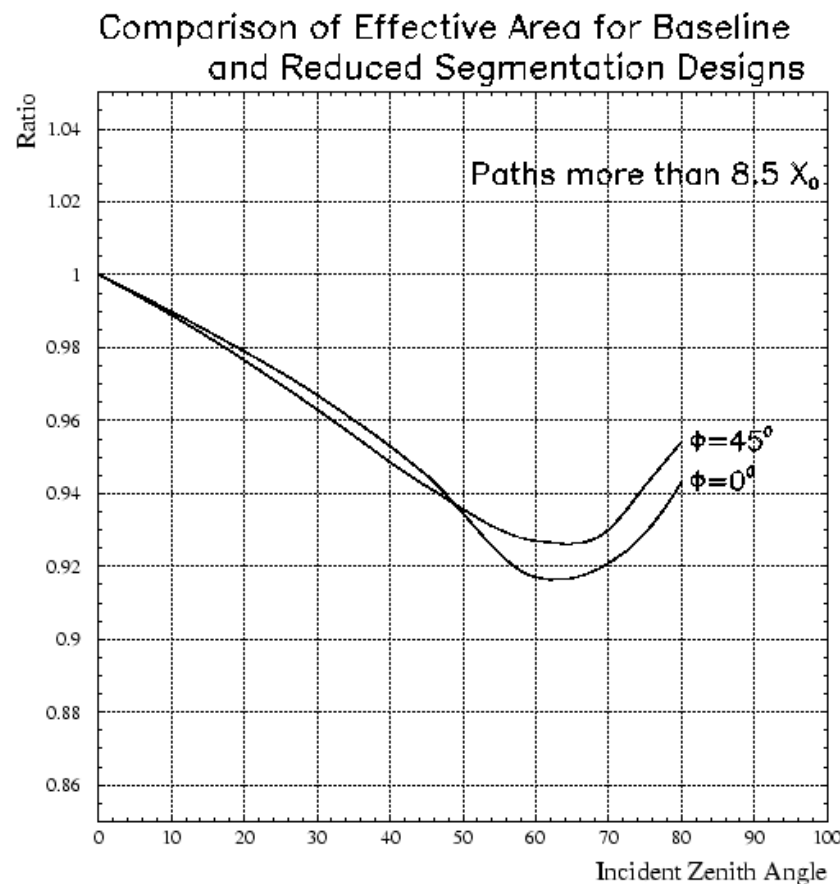
Effective Area reduction due to backslash





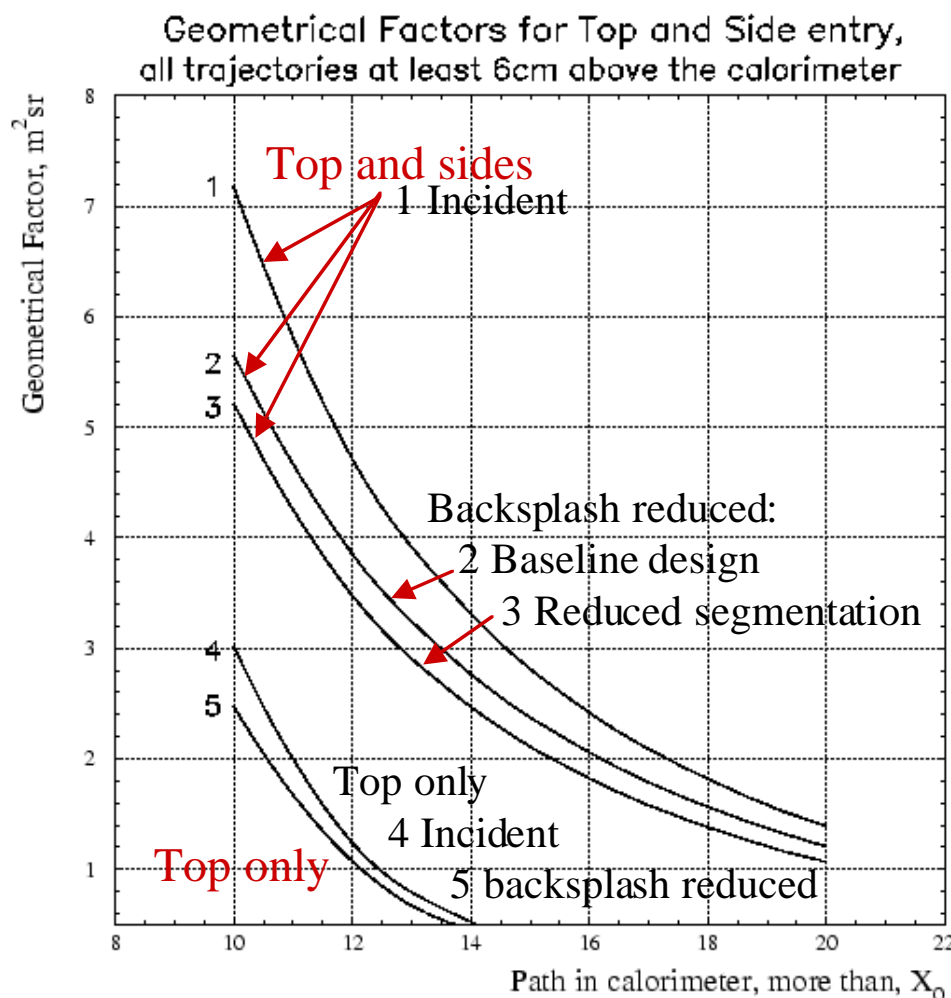
Effective Area reduction

- Ratio of effective area of reduced segmentation design to that for baseline design as function of incidence angle.
- Backsplash is included.
- Required path in calorimeter is $8.5X_0$.
- All events entering GLAST through the top and sides.
- All 4 ACD side rows are used
- Events are allowed to enter 6cm above the calorimeter.
- Azimuthal angle
 - $\Phi = 0^\circ$
 - $\Phi = 45^\circ$





Baseline geometry factor, “G”



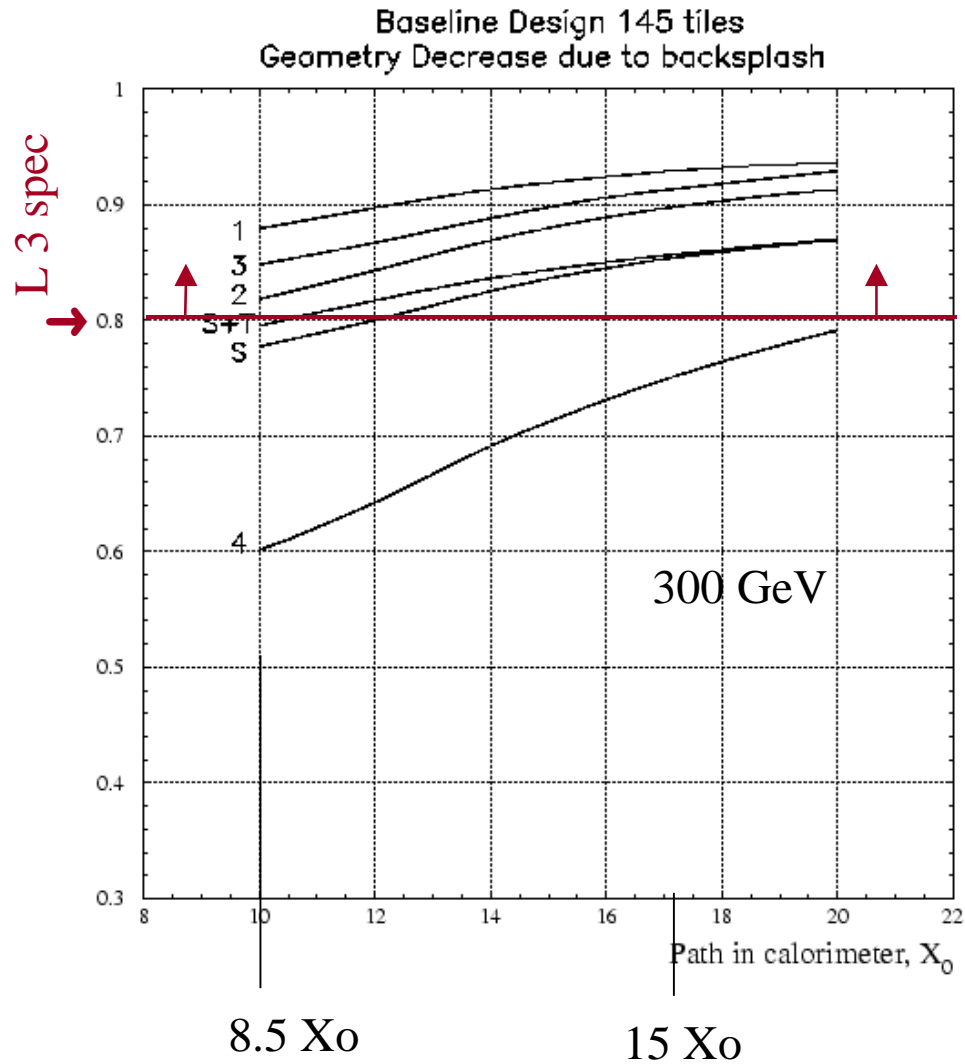
$$G(X_0) = A\Omega(X_0)$$

Integral geometry factor (area x solid angle) for LAT for paths greater than X_0 as a function of path length in X_0 (radiation lengths).

Note that more than 1/3 of LAT's “G” has $X_0 > 16$ radiation lengths.



Baseline design: loss due to self veto



Overall geometry through side and top (S+T) meets the requirement of 80% acceptance.

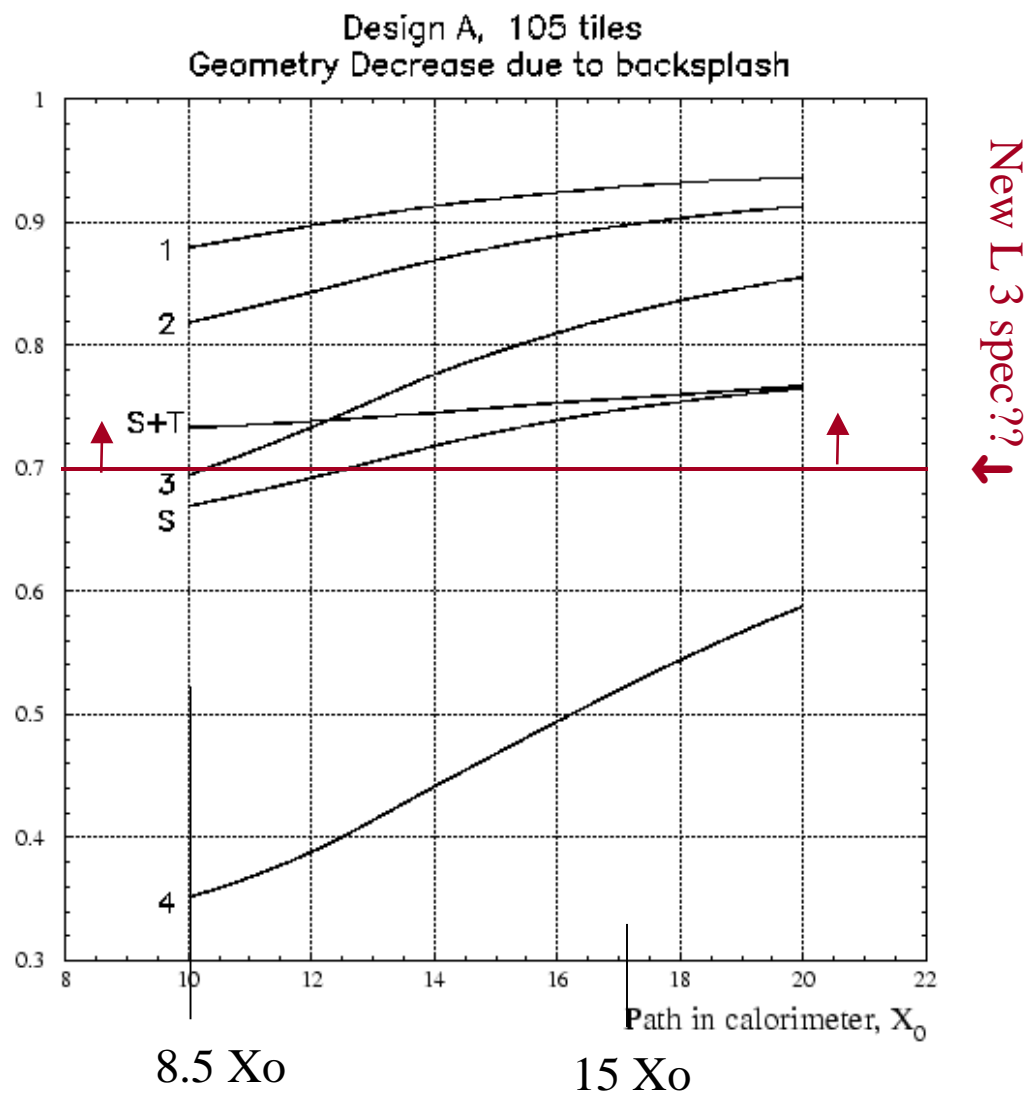
The loss through the side is worst through the bottom row of tiles nearest to the calorimeter.



Reduced segmentation: loss due to self veto

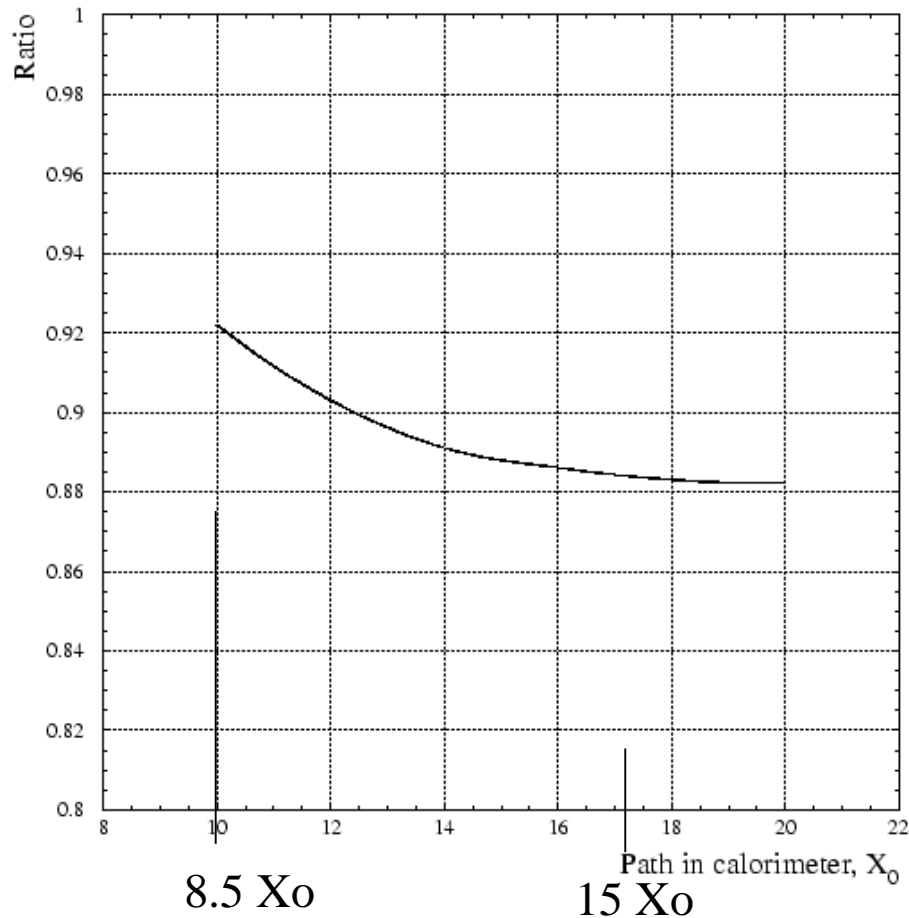
Tile size on bottom two rows is doubled in reduced segmentation design.

The overall effect is to reduce the effective geometry at 300 GeV **<27%** relative to that when there is no self-veto effect.



Reduced segmentation design relative to baseline

Comparison of G for Baseline and A designs



Conclusion:

Doubling the size of the tiles on the lower two rows will decrease the geometry factor of LAT to an isotropic background by $10 \pm 2\%$.

LAT would still have $>1/3$ of its “G” with $>16 X_0$.



ACD Level 3 specification

As of today, the DRAFT ACD Level 3 subsystem specification says:

- **5.6: False VETO due to Calorimeter Backsplash**
 - **<20% of otherwise accepted gamma-ray events at 300 GeV shall be rejected by false VETOs due to calorimeter backslash**
- **Assuming peak A_{eff} (at ~10 GeV) >8000 cm²**
 - Baseline meets LAT Requirement: A_{eff} >6400 cm² (TBR) at 300 GeV.**
 - Cannot reach the Goal: >9500 cm² at 1 TeV.**
- **Showed >0.73 can be attained w/ reduced segmentation proposed**
 - **To meet all requirements as stated, the**
Effective area at 10 GeV would have to be $>6400\text{cm}^2/0.73 = 8770\text{ cm}^2$
- **Therefore I recommend changing Level 3 spec to read:**
- **5.6: False VETO due to Calorimeter Backsplash**
 - **<30% of otherwise accepted gamma-ray events at 300 GeV shall be rejected by false VETOs due to calorimeter backslash**
 - **Implies A_{eff} could be as low as 5600 cm²**



Summary

- For baseline design, the geometric area self-veto reduction is <25%.
- Reduced segmentation design further reduces the effective area by less than an additional 8.5% (worst case).
- With Baseline design we meet “20% self-veto reduction at 300 GeV” requirements.
- Reduced segmentation design reduces GLAST geometry factor by less than 10% additional at 300 GeV.
 - For longer paths in the calorimeter the new design has slightly more G reduction (about 12%).



Conclusions

- Change the L3 additional loss specification from 20% to 30%
- In LAT Performance Specification 5.2.1
 - Change: “>6400 cm² (TBR) at 300 GeV”
 - To: “>5600 cm² at 300 GeV”
- Proceed to PDR with reduced segmentation in bottom two rows on side
 - 105 tiles instead of 145 tiles
 - Each side row would have 5 tiles
- No way to reach goal of $A_{\text{eff}} > 9500 \text{ cm}^2$ at 1 TeV.
 - Estimate 60% self-veto at 1 TeV
 - Meeting Peak A_{eff} goal of 10,000 cm² \Rightarrow 4000 cm² at TeV
 - Since electrons are relatively less of a problem at higher energies, we might do better by using the tracker as a self-shielded device.



Further work

- Determine calorimeter depth necessary to get required off-axis energy resolution of 6% (goal 6%).
- Validate use of “calorimeter only” events entering through the back 15 cm.
- Determine off-axis energy resolution as function of path length in calorimeter.
- Electron background rejection and loss of effective G and A_{eff} .
 - 10 GeV worst case
 - Higher energies as electron flux decreases relative to γ s
- Study use of tracker as a self-shielded device at energies above 300 GeV.
 - Self-veto becomes 2.2 x more serious at 1 TeV
 - Use very fine segmentation of tracker
- Assure simulations correctly reproduce backsplash results.